

# **Graphs in Machine Learning**

## Michal Valko

## Inria Lille - Nord Europe, France

TA: Pierre Perrault

Partially based on material by: Ulrike von Luxburg, Gary Miller, Mikhail Belkin

October 17th, 2018

MVA 2018/2019

## **Previous Lecture**

spectral graph theory

Laplacians and their properties

symmetric and asymmetric normalization

random walks

recommendation on a bipartite graph

resistive networks

- recommendation score as a resistance?
- Laplacian and resistive networks
- resistance distance and random walks



## **This Lecture**

geometry of the data and the connectivity

- spectral clustering
- manifold learning with Laplacians eigenmaps
- Gaussian random fields and harmonic solution
- graph-based semi-supervised learning and manifold regularization
- transductive learning

inductive and transductive semi-supervised learning



## Next Class: Lab Session

- 24. 10. 2018 by Pierre Perrault
- cca. 13h30-14h00 optional help with setup, 14h00-16h00: TD
- Bât. d'Alembert Amphi Curie
- The VM image will be available a day before the class
- Matlab/Octave or Python
- Short written report (graded)
- ▶ All homeworks together account for 40% of the final grade

## Content

- Graph Construction
- Test sensitivity to parameters:  $\sigma$ , k,  $\varepsilon$
- Spectral Clustering
- Spectral Clustering vs. k-means
- Image Segmentation



# Spectral Clustering: Cuts on graphs





# Spectral Clustering: Cuts on graphs



## Defining the cut objective we get the clustering!



## Spectral Clustering: Cuts on graphs



MinCut: 
$$\operatorname{cut}(A,B) = \sum_{i \in A, j \in B} w_{ij}$$



Can be solved efficiently, but maybe not what we want . . . .



# **Spectral Clustering: Balanced Cuts**

Let's balance the cuts!

## MinCut

$$\operatorname{cut}(A,B) = \sum_{i \in A, j \in B} w_{ij}$$

## RatioCut

$$\operatorname{RatioCut}(A, B) = \sum_{i \in A, j \in B} w_{ij} \left( \frac{1}{|A|} + \frac{1}{|B|} \right)$$

## Normalized Cut

$$\operatorname{NCut}(A, B) = \sum_{i \in A, j \in B} w_{ij} \left( \frac{1}{\operatorname{vol}(A)} + \frac{1}{\operatorname{vol}(B)} \right)$$



## **Spectral Clustering: Balanced Cuts**

$$\operatorname{RatioCut}(A, B) = \operatorname{cut}(A, B) \left(\frac{1}{|A|} + \frac{1}{|B|}\right)$$
$$\operatorname{NCut}(A, B) = \operatorname{cut}(A, B) \left(\frac{1}{\operatorname{vol}(A)} + \frac{1}{\operatorname{vol}(B)}\right)$$
Easily generalizable to  $k \ge 2$ 

Can we compute this? RatioCut and NCut are NP hard :(

Approximate!



Relaxation for (simple) balanced cuts for 2 sets

$$\min_{A,B} \operatorname{cut}(A,B) \quad \text{s.t.} \quad |A| = |B|$$

Graph function **f** for cluster membership: 
$$f_i = \begin{cases} 1 & \text{if } V_i \in A, \\ -1 & \text{if } V_i \in B. \end{cases}$$

What it is the cut value with this definition?

$$\operatorname{cut}(A,B) = \sum_{i \in A, j \in B} w_{i,j} = \frac{1}{4} \sum_{i,j} w_{i,j} (f_i - f_j)^2 = \frac{1}{2} \mathbf{f}^{\mathsf{T}} \mathbf{L} \mathbf{f}$$

What is the relationship with the smoothness of a graph function?



$$\operatorname{cut}(A,B) = \sum_{i \in A, j \in B} w_{i,j} = \frac{1}{4} \sum_{i,j} w_{i,j} (f_i - f_j)^2 = \frac{1}{2} \mathbf{f}^\mathsf{T} \mathsf{L} \mathbf{f}$$
$$\mathsf{A}| = |B| \implies \sum_i f_i = 0 \implies \mathbf{f} \perp \mathbf{1}_N$$
$$\mathbf{f}|| = \sqrt{N}$$

## objective function of spectral clustering

$$\min_{\mathbf{f}} \mathbf{f}^{\mathsf{T}} \mathbf{L} \mathbf{f} \quad \text{s.t.} \quad f_i = \pm 1, \quad \mathbf{f} \perp \mathbf{1}_{\mathsf{N}}, \quad \|\mathbf{f}\| = \sqrt{\mathsf{N}}$$

Still NP hard : (  $\rightarrow$  Relax even further!

$$f_i \rightarrow f_i \in \mathbb{R}$$

Michal Valko – Graphs in Machine Learning

objective function of spectral clustering

 $\min_{\mathbf{f}} \mathbf{f}^{\mathsf{T}} \mathbf{L} \mathbf{f} \quad \text{s.t.} \quad f_i \in \mathbb{R}, \quad \mathbf{f} \perp \mathbf{1}_N, \quad \|\mathbf{f}\| = \sqrt{N}$ 

## Rayleigh-Ritz theorem

If  $\lambda_1 \leq \cdots \leq \lambda_N$  are the eigenvectors of real symmetric **L** then

$$\lambda_{1} = \min_{\mathbf{x} \neq 0} \frac{\mathbf{x}^{\mathsf{T}} \mathbf{L} \mathbf{x}}{\mathbf{x}^{\mathsf{T}} \mathbf{x}} = \min_{\mathbf{x}^{\mathsf{T}} \mathbf{x}=1} \mathbf{x}^{\mathsf{T}} \mathbf{L} \mathbf{x}$$
$$\lambda_{N} = \max_{\mathbf{x} \neq 0} \frac{\mathbf{x}^{\mathsf{T}} \mathbf{L} \mathbf{x}}{\mathbf{x}^{\mathsf{T}} \mathbf{x}} = \max_{\mathbf{x}^{\mathsf{T}} \mathbf{x}=1} \mathbf{x}^{\mathsf{T}} \mathbf{L} \mathbf{x}$$

 $\frac{\mathbf{x}^{\mathsf{T}}\mathbf{L}\mathbf{x}}{\mathbf{x}^{\mathsf{T}}\mathbf{x}} \equiv \mathsf{Rayleigh} \mathsf{ quotient}$ 

How can we use it?



objective function of spectral clustering

 $\min_{\mathbf{f}} \mathbf{f}^{\mathsf{T}} \mathbf{L} \mathbf{f} \quad \text{s.t.} \quad f_i \in \mathbb{R}, \quad \mathbf{f} \perp \mathbf{1}_N, \quad \|\mathbf{f}\| = \sqrt{N}$ 

Generalized Rayleigh-Ritz theorem (Courant-Fischer-Weyl)

If  $\lambda_1 \leq \cdots \leq \lambda_N$  are the eigenvectors of real symmetric **L** and  $\mathbf{v}_1, \ldots, \mathbf{v}_N$  the corresponding orthogonal eigenvalues, then for k = 1 : N - 1

$$\lambda_{k+1} = \min_{\mathbf{x} \neq 0, \mathbf{x} \perp \mathbf{v}_1, \dots \mathbf{v}_k} \frac{\mathbf{x}^{\mathsf{T}} \mathbf{L} \mathbf{x}}{\mathbf{x}^{\mathsf{T}} \mathbf{x}} = \min_{\mathbf{x}^{\mathsf{T}} \mathbf{x} = 1, \mathbf{x} \perp \mathbf{v}_1, \dots \mathbf{v}_k} \mathbf{x}^{\mathsf{T}} \mathbf{L} \mathbf{x}$$
$$\lambda_{N-k} = \max_{\mathbf{x} \neq 0, \mathbf{x} \perp \mathbf{v}_n, \dots \mathbf{v}_{N-k+1}} \frac{\mathbf{x}^{\mathsf{T}} \mathbf{L} \mathbf{x}}{\mathbf{x}^{\mathsf{T}} \mathbf{x}} = \max_{\mathbf{x}^{\mathsf{T}} \mathbf{x} = 1, \mathbf{x} \perp \mathbf{v}_N, \dots \mathbf{v}_{N-k+1}} \mathbf{x}^{\mathsf{T}} \mathbf{L} \mathbf{x}$$



# Rayleigh-Ritz theorem: Quick and dirty proof

When we reach the extreme points?

$$\frac{\partial}{\partial \mathbf{x}} \left( \frac{\mathbf{x}^{\mathsf{T}} \mathbf{L} \mathbf{x}}{\mathbf{x}^{\mathsf{T}} \mathbf{x}} \right) = \frac{\partial}{\partial \mathbf{x}} \left( \frac{f(\mathbf{x})}{g(\mathbf{x})} \right) = 0 \iff f'(\mathbf{x})g(\mathbf{x}) = f(\mathbf{x})g'(\mathbf{x})$$

By matrix calculus (or just calculus):

$$\frac{\partial \mathbf{x}^{\mathsf{T}} \mathbf{L} \mathbf{x}}{\partial \mathbf{x}} = 2\mathbf{L} \mathbf{x} \text{ and } \frac{\partial \mathbf{x}^{\mathsf{T}} \mathbf{x}}{\partial \mathbf{x}} = 2\mathbf{x}$$

When  $f'(\mathbf{x})g(\mathbf{x}) = f(\mathbf{x})g'(\mathbf{x})$ ?

$$\mathbf{L}\mathbf{x}(\mathbf{x}^{\mathsf{T}}\mathbf{x}) = (\mathbf{x}^{\mathsf{T}}\mathbf{L}\mathbf{x})\mathbf{x} \iff \mathbf{L}\mathbf{x} = \frac{\mathbf{x}^{\mathsf{T}}\mathbf{L}\mathbf{x}}{\mathbf{x}^{\mathsf{T}}\mathbf{x}}\mathbf{x} \iff \mathbf{L}\mathbf{x} = \lambda\mathbf{x}$$

Conclusion: Extremes are the eigenvectors with their eigenvalues



objective function of spectral clustering

$$\min_{\mathbf{f}} \mathbf{f}^{\mathsf{T}} \mathbf{L} \mathbf{f} \quad \text{s.t.} \quad f_i \in \mathbb{R}, \quad \mathbf{f} \perp \mathbf{1}_{\mathsf{N}}, \quad \|\mathbf{f}\| = \sqrt{\mathsf{N}}$$

Solution: **second eigenvector** How do we get the clustering? The solution may not be integral. What to do?

cluster<sub>i</sub> = 
$$\begin{cases} 1 & \text{if } f_i \geq 0, \\ -1 & \text{if } f_i < 0. \end{cases}$$

Works but this heuristics is often too simple. In practice, cluster **f** using *k*-means to get  $\{C_i\}_i$  and assign:

$$\operatorname{cluster}_{i} = \begin{cases} 1 & \text{if } i \in C_{1}, \\ -1 & \text{if } i \in C_{-1}. \end{cases}$$



# Spectral Clustering: Approximating RatioCut

Wait, but we did not care about approximating mincut!

## RatioCut

nnía

$$\operatorname{RatioCut}(A,B) = \sum_{i \in A, j \in B} w_{ij} \left( \frac{1}{|A|} + \frac{1}{|B|} \right)$$

Define graph function  $\mathbf{f}$  for cluster membership of RatioCut:

$$f_i = \begin{cases} \sqrt{\frac{|B|}{|A|}} & \text{if } V_i \in A, \\ -\sqrt{\frac{|A|}{|B|}} & \text{if } V_i \in B. \end{cases}$$

$$\mathbf{f}^{\mathsf{T}}\mathbf{L}\mathbf{f} = \frac{1}{2}\sum_{i,j} w_{i,j}(f_i - f_j)^2 = (|A| + |B|) \operatorname{RatioCut}(A, B)$$

# Spectral Clustering: Approximating RatioCut

Define graph function  $\mathbf{f}$  for cluster membership of RatioCut:

$$f_i = egin{cases} \sqrt{|B| \over |A|} & ext{if } V_i \in A, \ -\sqrt{|A| \over |B|} & ext{if } V_i \in B. \ \sum_i f_i = 0 \ \sum_i f_i^2 = N \end{cases}$$

objective function of spectral clustering (same - it's magic!)

 $\min_{\mathbf{f}} \mathbf{f}^{\mathsf{T}} \mathbf{L} \mathbf{f} \quad \text{s.t.} \quad f_i \in \mathbb{R}, \quad \mathbf{f} \perp \mathbf{1}_N, \quad \|\mathbf{f}\| = \sqrt{N}$ 



# Spectral Clustering: Approximating NCut

## Normalized Cut

nnía

$$\operatorname{NCut}(A, B) = \sum_{i \in A, j \in B} w_{ij} \left( \frac{1}{\operatorname{vol}(A)} + \frac{1}{\operatorname{vol}(B)} \right)$$

Define graph function  $\mathbf{f}$  for cluster membership of NCut:

$$f_i = \begin{cases} \sqrt{\frac{\operatorname{vol}(A)}{\operatorname{vol}(B)}} & \text{if } V_i \in A, \\ -\sqrt{\frac{\operatorname{vol}(B)}{\operatorname{vol}(A)}} & \text{if } V_i \in B. \end{cases}$$
$$\mathbf{D}\mathbf{f})^{\mathsf{T}}\mathbf{1}_n = 0 \qquad \mathbf{f}^{\mathsf{T}}\mathbf{D}\mathbf{f} = \operatorname{vol}(\mathcal{V}) \qquad \mathbf{f}^{\mathsf{T}}\mathbf{L}\mathbf{f} = \operatorname{vol}(\mathcal{V})\operatorname{NCut}(A, B)$$

objective function of spectral clustering (NCut)

min  $\mathbf{f}^{\mathsf{T}} \mathbf{L} \mathbf{f}$  s.t.  $f_i \in \mathbb{R}$ ,  $\mathbf{D} \mathbf{f} \perp \mathbf{1}_N$ ,  $\mathbf{f}^{\mathsf{T}} \mathbf{D} \mathbf{f} = \operatorname{vol}(\mathcal{V})$ 



# **Spectral Clustering: Approximating NCut**

objective function of spectral clustering (NCut)

 $\min_{f} \mathbf{f}^{\mathsf{T}} \mathbf{L} \mathbf{f} \quad \text{s.t.} \quad f_{i} \in \mathbb{R}, \quad \mathbf{D} \mathbf{f} \perp \mathbf{1}_{N}, \quad \mathbf{f}^{\mathsf{T}} \mathbf{D} \mathbf{f} = \operatorname{vol}(\mathcal{V})$ 

Can we apply Rayleigh-Ritz now? Define  $\mathbf{w} = \mathbf{D}^{1/2} \mathbf{f}$ 

objective function of spectral clustering (NCut)

$$\min_{\mathbf{w}} \mathbf{w}^{\mathsf{T}} \mathbf{D}^{-1/2} \mathbf{L} \mathbf{D}^{-1/2} \mathbf{w} \quad \text{s.t.} \quad w_i \in \mathbb{R}, \mathbf{w} \perp \mathbf{D}^{1/2} \mathbf{1}_N, \|\mathbf{w}\|^2 = \text{vol}(\mathcal{V})$$

objective function of spectral clustering (NCut)

$$\min_{\mathbf{w}} \mathbf{w}^{\mathsf{T}} \mathbf{L}_{\text{sym}} \mathbf{w} \quad \text{s.t.} \quad w_i \in \mathbb{R}, \quad \mathbf{w} \perp \mathbf{v}_{1, \mathbf{L}_{\text{sym}}}, \quad \|\mathbf{w}\|^2 = \text{vol}(\mathcal{V})$$



# Spectral Clustering: Approximating NCut

objective function of spectral clustering (NCut)

 $\min_{\mathbf{w}} \mathbf{w}^{\mathsf{T}} \mathbf{L}_{\text{sym}} \mathbf{w} \quad \text{s.t.} \quad w_{i} \in \mathbb{R}, \quad \mathbf{w} \perp \mathbf{v}_{1, \mathbf{L}_{\text{sym}}}, \quad \|\mathbf{w}\| = \text{vol}(\mathcal{V})$ 

Solution by Rayleigh-Ritz?  $w = v_{2,L_{sym}} f = D^{-1/2}w$ 

 $\boldsymbol{f}$  is a the second eigenvector of  $\boldsymbol{L}_{\mathrm{rw}}$  !

tl;dr: Get the second eigenvector of  $L/L_{\rm rw}$  for RatioCut/NCut.



# **Spectral Clustering: Approximation**

These are all approximations. How bad can they be?

Example: cockroach graphs



## No efficient approximation exist. Other relaxations possible.

https://www.cs.cmu.edu/~glmiller/Publications/Papers/GuMi95.pdf



## Spectral Clustering: 1D Example

## Elbow rule/EigenGap heuristic for number of clusters









# **Spectral Clustering: Understanding:**

Compactness vs. Connectivity



For which kind of data we can use one vs. the other? Any disadvantages of spectral clustering?



# Spectral Clustering: 1D Example - Histogram



http://www.informatik.uni-hamburg.de/ML/contents/people/luxburg/
publications/Luxburg07\_tutorial.pdf



## Spectral Clustering: 1D Example - Eigenvectors





## Spectral Clustering: Bibliography

- M. Meila et al. "A random walks view of spectral segmentation". In: International Conference on Artificial Intelligence and Statistics (2001)
- L<sub>sym</sub> Andrew Y Ng, Michael I Jordan, and Yair Weiss. "On spectral clustering: Analysis and an algorithm". In: Neural Information Processing Systems. 2001
- L<sub>rm</sub> J Shi and J Malik. "Normalized Cuts and Image Segmentation". In: *IEEE Transactions on Pattern Analysis* and Machine Intelligence 22 (2000), pp. 888–905
- Things can go wrong with the relaxation: Daniel A. Spielman and Shang H. Teng. "Spectral partitioning works: Planar graphs and finite element meshes". In: *Linear Algebra and Its Applications* 421 (2007), pp. 284–305



# $\mathbb{R}^{d} \rightarrow \mathbb{R}^{m}$ manifold learning ...discworld

Ínría

# Manifold Learning: Recap

## problem: definition reduction/manifold learning

Given  $\{\mathbf{x}_i\}_{i=1}^N$  from  $\mathbb{R}^d$  find  $\{\mathbf{y}_i\}_{i=1}^N$  in  $\mathbb{R}^m$ , where  $m \ll d$ .

What do we know about the dimensionality reduction

- representation/visualization (2D or 3D)
- an old example: globe to a map
- often assuming  $\mathcal{M} \subset \mathbb{R}^d$
- feature extraction

linear vs. nonlinear dimensionality reduction

What do we know about linear vs. nonlinear methods?

linear: ICA, PCA, SVD, ...

nonlinear often preserve only local distances



## Manifold Learning: Linear vs. Non-linear



Ínría

Michal Valko - Graphs in Machine Learning

## Manifold Learning: Preserving (just) local distances



 $d(\mathbf{y}_i, \mathbf{y}_j) = d(\mathbf{x}_i, \mathbf{x}_j)$  only if  $d(\mathbf{x}_i, \mathbf{x}_j)$  is small

$$\min\sum_{ij}w_{ij}\|\mathbf{y}_i-\mathbf{y}_j\|^2$$

Looks familiar?



# Manifold Learning: Laplacian Eigenmaps

Step 1: Solve generalized eigenproblem:

 $\mathbf{L}\mathbf{f} = \lambda \mathbf{D}\mathbf{f}$ 

Step 2: Assign *m* new coordinates:

$$\mathbf{x}_{i}\mapsto\left(f_{2}\left(i\right),\ldots,f_{m+1}\left(i\right)\right)$$

**Note**<sub>1</sub>: we need to get m + 1 smallest eigenvectors **Note**<sub>2</sub>: **f**<sub>1</sub> is useless

http://web.cse.ohio-state.edu/~mbelkin/papers/LEM\_NC\_03.pdf



# Manifold Learning: Laplacian Eigenmaps to 1D

Laplacian Eigenmaps 1D objective

 $\min_{\mathbf{f}} \mathbf{f}^{\mathsf{T}} \mathbf{L} \mathbf{f} \quad \text{s.t.} \quad f_i \in \mathbb{R}, \quad \mathbf{f}^{\mathsf{T}} \mathbf{D} \mathbf{1} = \mathbf{0}, \quad \mathbf{f}^{\mathsf{T}} \mathbf{D} \mathbf{f} = \mathbf{1}$ 

The meaning of the constraints is similar as for spectral clustering:

 $\mathbf{f}^{\scriptscriptstyle\mathsf{T}} \mathbf{D} \mathbf{f} = \mathbf{1} \text{ is for scaling}$ 

 $\mathbf{f}^{\scriptscriptstyle\mathsf{T}}\mathbf{D}\mathbf{1}=\mathbf{0}$  is to not get  $\mathbf{v}_1$ 

What is the solution?



# Manifold Learning: Example



http://www.mathworks.com/matlabcentral/fileexchange/ 36141-laplacian-eigenmap-~-diffusion-map-~-manifold-learning



SSL semi-supervised learning ...our running example for learning with graphs

Innia

# Semi-supervised learning: How is it possible?



## This is how children learn! hypothesis



# Semi-supervised learning (SSL)

## SSL problem: definition

Given  $\{\mathbf{x}_i\}_{i=1}^N$  from  $\mathbb{R}^d$  and  $\{y_i\}_{i=1}^{n_i}$ , with  $n_l \ll N$ , find  $\{y_i\}_{i=n_l+1}^n$  (transductive) or find f predicting y well beyond that (inductive).

## Some facts about **SSL**

- assumes that the unlabeled data is useful
- works with data geometry assumptions
  - cluster assumption low-density separation
  - manifold assumption
  - smoothness assumptions, generative models, ...
- now it helps now, now it does not (sic)
  - provable cases when it helps
- inductive or transductive/out-of-sample extension

http://olivier.chapelle.cc/ssl-book/discussion.pdf



# **SSL:** Self-Training





# SSL: Overview: Self-Training

## SSL: Self-Training

Input: 
$$\mathcal{L} = \{\mathbf{x}_i, y_i\}_{i=1}^{n_l}$$
 and  $\mathcal{U} = \{\mathbf{x}_i\}_{i=n_l+1}^{N}$   
Repeat:

▶ train f using  $\mathcal{L}$ 

• apply f to (some)  $\mathcal{U}$  and add them to  $\mathcal{L}$ 

## What are the properties of self-training?

- its a wrapper method
- heavily depends on the the internal classifier
- some theory exist for specific classifiers
- nobody uses it anymore
- errors propagate (unless the clusters are well separated)



## SSL: Self-Training: Bad Case



Inría

Michal Valko – Graphs in Machine Learning

# SSL: Transductive SVM: S3VM



Inría

Michal Valko – Graphs in Machine Learning

# SSL: Transductive SVM: Classical SVM

Linear case:  $f = \mathbf{w}^{\mathsf{T}}\mathbf{x} + b \quad \rightarrow \quad \text{we look for } (\mathbf{w}, b)$ 

max-margin classification

$$\max_{\mathbf{w},b} \quad \frac{1}{\|\mathbf{w}\|} \\ s.t. \quad y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \ge 1 \quad \forall i = 1, \dots, n_i$$

note the difference between functional and geometric margin

## max-margin classification

$$\min_{\mathbf{w},b} \|\mathbf{w}\|^2$$
s.t.  $y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \ge 1 \quad \forall i = 1, \dots, n_l$ 



# SSL: Transductive SVM: Classical SVM

## max-margin classification: separable case

$$\min_{\mathbf{w},b} \|\mathbf{w}\|^2$$
  
s.t.  $y_i(\mathbf{w}^\mathsf{T}\mathbf{x}_i + b) \ge 1 \quad \forall i = 1, \dots, n_l$ 

## max-margin classification: non-separable case

$$\min_{\mathbf{w},b} \quad \frac{\lambda}{\|\mathbf{w}\|^2} + \sum_i \xi_i$$
s.t.  $y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \ge 1 - \xi_i \quad \forall i = 1, \dots, n_i$ 
 $\xi_i \ge 0 \quad \forall i = 1, \dots, n_i$ 



# SSL: Transductive SVM: Classical SVM

max-margin classification: non-separable case

$$\min_{\mathbf{w},b} \quad \lambda \|\mathbf{w}\|^2 + \sum_i \xi_i$$
s.t. 
$$y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \ge 1 - \xi_i \quad \forall i = 1, \dots, n_i$$

$$\xi_i \ge 0 \quad \forall i = 1, \dots, n_i$$

Unconstrained formulation using hinge loss:

$$\min_{\mathbf{w},b}\sum_{i}^{n_{i}}\max\left(1-y_{i}\left(\mathbf{w}^{\mathsf{T}}\mathbf{x}_{i}+b\right),0\right)+\lambda\|\mathbf{w}\|^{2}$$

In general?

$$\min_{\mathbf{w},b}\sum_{i}^{n_{l}}V(\mathbf{x}_{i},y_{i},f(\mathbf{x}_{i}))+\lambda\Omega(f)$$

## SSL: Transductive SVM: Classical SVM: Hinge loss



$$V(\mathbf{x}_{i}, y_{i}, f(\mathbf{x}_{i})) = \max\left(1 - y_{i}\left(\mathbf{w}^{\mathsf{T}}\mathbf{x}_{i} + b\right), 0\right)$$



## SSL: Transductive SVM: Unlabeled Examples

$$\min_{\mathbf{w},b}\sum_{i}^{n_{l}}\max\left(1-y_{i}\left(\mathbf{w}^{\mathsf{T}}\mathbf{x}_{i}+b\right),0\right)+\lambda\|\mathbf{w}\|^{2}$$

How to incorporate unlabeled examples?

No y's for unlabeled  $\mathbf{x}$ .

**Prediction of** f for (any) x? 
$$\hat{y} = \operatorname{sgn}(f(\mathbf{x})) = \operatorname{sgn}(\mathbf{w}^{\mathsf{T}}\mathbf{x} + b)$$

Pretending that sgn  $(f(\mathbf{x}))$  is the true label ...

$$V(\mathbf{x}, \hat{y}, f(\mathbf{x})) = \max (1 - \hat{y} (\mathbf{w}^{\mathsf{T}} \mathbf{x} + b), 0)$$
  
= max (1 - sgn ( $\mathbf{w}^{\mathsf{T}} \mathbf{x} + b$ ) ( $\mathbf{w}^{\mathsf{T}} \mathbf{x} + b$ ), 0)  
= max (1 - | $\mathbf{w}^{\mathsf{T}} \mathbf{x} + b$ |, 0)



## SSL: Transductive SVM: Hinge and Hat Loss





# SSL: Transductive SVM: S3VM



## This is what we wanted!



## SSL: Transductive SVM: Formulation

Main SVM idea stays the same: penalize the margin  

$$\min_{\mathbf{w},b} \sum_{i=1}^{n_l} \max \left(1 - y_i \left(\mathbf{w}^{\mathsf{T}} \mathbf{x}_i + b\right), 0\right) + \lambda_1 \|\mathbf{w}\|^2 + \lambda_2 \sum_{i=n_l+1}^{n_l+n_u} \max \left(1 - |\mathbf{w}^{\mathsf{T}} \mathbf{x}_i + b|, 0\right)$$

What is the loss and what is the regularizer?  $\min_{\mathbf{w},b} \sum_{i=1}^{n_l} \max\left(1 - y_i \left(\mathbf{w}^{\mathsf{T}} \mathbf{x}_i + b\right), 0\right) + \lambda_1 \|\mathbf{w}\|^2 + \lambda_2 \sum_{i=n_l+1}^{n_l+n_u} \max\left(1 - |\mathbf{w}^{\mathsf{T}} \mathbf{x}_i + b|, 0\right)$ 

Think of unlabeled data as the regularizers for your classifiers!

Practical hint: Additionally enforce the class balance.

## What it the main issue of TSVM?

recent advancements: http://jmlr.org/proceedings/papers/v48/hazanb16.pdf



## Next class: TD, Wednesday October 24th at 14:00!





Michal Valko michal.valko@inria.fr ENS Paris-Saclay, MVA 2018/2019 SequeL team, Inria Lille — Nord Europe https://team.inria.fr/sequel/