

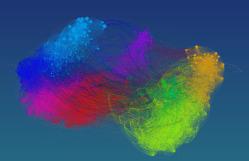
Graphs in Machine Learning

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Partially based on material by: Ulrike von Luxburg, Gary Miller, Doyle & Schnell, Daniel Spielman



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Previous Lecture

- where do the graphs come from?
 - social, information, utility, and biological networks
 - we create them from the flat data
 - random graph models
- specific applications and concepts
 - maximizing influence on a graph gossip propagation, submodularity, proof of the approximation guarantee
 - Google pagerank random surfer process, steady state vector, sparsity
 - online semi-supervised learning label propagation, backbone graph, online learning, combinatorial sparsification, stability analysis
 - ► Erdős number project, real-world graphs, heavy tails, small world when did this happen?



This Lecture

- similarity graphs
 - different types
 - construction
 - practical considerations
- ► Laplacians and their properties
- spectral graph theory
- random walks
- recommendation on a bipartite graph
- resistive networks
 - recommendation score as a resistance?
 - Laplacian and resistive networks
 - resistance distance and random walks

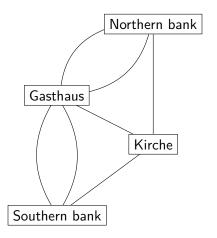


Graph theory refresher





Graph theory refresher





Graph theory refresher

- 250 years of graph theory
- Seven Bridges of Königsberg (Leonhard Euler, 1735)
- necessary for Eulerian circuit: 0 or 2 nodes of odd degree
- ▶ after bombing and rebuilding there are now 5 bridges in Kaliningrad for the nodes with degrees [2, 2, 3, 3]
- the original problem is solved but not practical http://people.engr.ncsu.edu/mfms/SevenBridges/



Similarity Graphs

Input: $x_1, x_2, x_3, ..., x_N$

- raw data
- ▶ flat data
- vectorial data





Similarity Graphs

Similarity graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ — (un)weighted

Task 1: For each pair i, j: define a **similarity function** s_{ij}

Task 2: Decide which edges to include

arepsilon-neighborhood graphs — connect the points with the distances smaller than arepsilon

k-NN neighborhood graphs – take *k* nearest neighbors fully connected graphs – consider everything

This is art (not much theory exists).

http://www.informatik.uni-hamburg.de/ML/contents/people/luxburg/publications/Luxburg07_tutorial.pdf



Similarity Graphs: ε -neighborhood graphs

Edges connect the points with the distances smaller than ε .

- lacktriangle distances are roughly on the same scale (arepsilon)
- lacktriangle weights may not bring additional info ightarrow unweighted
- ightharpoonup equivalent to: similarity function is at least arepsilon
- ▶ theory [Penrose, 1999]: $\varepsilon = ((\log N)/N)^d$ to guarantee connectivity N nodes, d dimension
- ▶ practice: choose ε as the length of the longest edge in the MST minimum spanning tree

What could be the problem with this MST approach?



Similarity Graphs: k-nearest neighbors graphs

Edges connect each node to its k-nearest neighbors.

- asymmetric (or directed graph)
 - ▶ option OR: ignore the direction
 - ▶ option AND: include if we have both direction (mutual *k*-NN)
- how to choose *k*?
- $k \approx \log N$ suggested by asymptotics (practice: up to \sqrt{N})
- \blacktriangleright for mutual k-NN we need to take larger k
- mutual k-NN does not connect regions with different density
- why don't we take k = N 1?



Similarity Graphs: Fully connected graphs

Edges connect everything.

- choose a "meaningful" similarity function s
- default choice:

$$s_{ij} = \exp\left(\frac{-\|\mathbf{x}_i - \mathbf{x}_j\|^2}{2\sigma^2}\right)$$

- why the exponential decay with the distance?
- \triangleright σ controls the width of the neighborhoods
 - ightharpoonup similar role as ε
 - ▶ a practical rule of thumb: 10% of the average empirical std
 - **possibility**: learn σ_i for each feature independently
- metric learning (a whole field of ML)



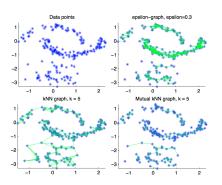
Similarity Graphs: Important considerations

- calculate all s_{ij} and threshold has its limits ($N \approx 10000$)
- graph construction step can be a huge bottleneck
- want to go higher? (we often have to)
 - down-sample
 - approximate NN
 - LSH Locally Sensitive Hashing
 - CoverTrees
 - Spectral sparsifiers
 - sometime we may not need the graph (just the final results)
 - yet another story: when we start with a large graph and want to make it sparse (later in the course)
- these rules have little theoretical underpinning
- similarity is very data-dependent



Similarity Graphs: ε or k-NN?

DEMO IN CLASS



http://www.ml.uni-saarland.de/code/GraphDemo/DemoSpectralClustering.htm http://www.informatik.uni-hamburg.de/ML/contents/people/luxburg/ publications/Luxburg07_tutorial.pdf



Generic Similarity Functions

Gaussian similarity function/Heat function/RBF:

$$s_{ij} = \exp\left(\frac{-\|\mathbf{x}_i - \mathbf{x}_j\|^2}{2\sigma^2}\right)$$

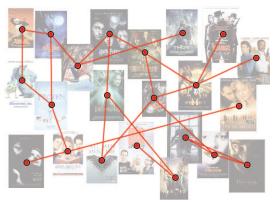
Cosine similarity function:

$$s_{ij} = \cos(\theta) = \left(\frac{\mathbf{x}_i^\mathsf{T} \mathbf{x}_j}{\|\mathbf{x}_i\| \|\mathbf{x}_j\|}\right)$$

Typical Kernels



Similarity Graphs



 $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ - with a set of **nodes** \mathcal{V} and a set of **edges** \mathcal{E}



Sources of Real Networks

- http://snap.stanford.edu/data/
- ▶ http://www-personal.umich.edu/~mejn/netdata/
- http://proj.ise.bgu.ac.il/sns/datasets.html
- http://www.cise.ufl.edu/research/sparse/matrices/
- http://vlado.fmf.uni-lj.si/pub/networks/data/ default.htm

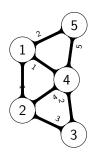


Graph Laplacian

 $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ - with a set of **nodes** \mathcal{V} and a set of **edges** \mathcal{E}

 $\begin{array}{ccc} \textbf{A} & \text{adjacency matrix} \\ \textbf{W} & \text{weight matrix} \\ \textbf{D} & \text{(diagonal) degree matrix} \\ \textbf{L} = \textbf{D} - \textbf{W} & \text{graph } \textbf{Laplacian} \text{ matrix} \\ \end{array}$

$$\mathbf{L} = \left(\begin{array}{ccccc} 4 & -1 & 0 & -1 & -2 \\ -1 & 8 & -3 & -4 & 0 \\ 0 & -3 & 5 & -2 & 0 \\ -1 & -4 & -2 & 12 & -5 \\ -2 & 0 & 0 & -5 & 7 \end{array} \right)$$



L is SDD!



Properties of Graph Laplacian

Graph function: a vector $\mathbf{f} \in \mathbb{R}^N$ assigning values to nodes:

$$f: \mathcal{V}(\mathcal{G}) \to \mathbb{R}$$
.

$$\mathbf{f}^{\mathsf{T}}\mathbf{L}\mathbf{f} = \frac{1}{2}\sum_{i,j\leq N}w_{i,j}(f_i - f_j)^2 = S_G(\mathbf{f})$$



Recap: Eigenwerte und Eigenvektoren

A vector \mathbf{v} is an eigenvector of matrix \mathbf{M} of eigenvalue λ

$$\mathbf{M}\mathbf{v} = \lambda \mathbf{v}$$
.

If $(\lambda_1, \mathbf{v}_1)$ are $(\lambda_2, \mathbf{v}_2)$ eigenpairs for symmetric \mathbf{M} with $\lambda_1 \neq \lambda_2$ then $\mathbf{v}_1 \perp \mathbf{v}_2$, i.e., $\mathbf{v}_1^\mathsf{T} \mathbf{v}_2 = 0$.

If (λ, \mathbf{v}_1) , (λ, \mathbf{v}_2) are eigenpairs for **M** then $(\lambda, \mathbf{v}_1 + \mathbf{v}_2)$ is as well.

For symmetric M, the multiplicity of λ is the dimension of the space of eigenvectors corresponding to λ .

Every $N \times N$ symmetric matrix has N eigenvalues (w/multiplicities).



Eigenvalues, Eigenvectors, and Eigendecomposition

A vector ${\bf v}$ is an **eigenvector** of matrix ${\bf M}$ of **eigenvalue** λ

$$Mv = \lambda v$$
.

Vectors $\{\mathbf{v}_i\}_i$ form an **orthonormal** basis with $\lambda_1 \leq \lambda_2 \leq \ldots \lambda_N$.

$$\forall i \quad \mathbf{M} \mathbf{v}_i = \lambda_i \mathbf{v}_i \equiv \mathbf{M} \mathbf{Q} = \mathbf{Q} \mathbf{\Lambda}$$

 ${f Q}$ has eigenvectors in columns and ${f \Lambda}$ has eigenvalues on its diagonal.

Right-multiplying $\mathbf{MQ} = \mathbf{Q} \mathbf{\Lambda}$ by \mathbf{Q}^{T} we get the eigendecomposition of \mathbf{M} :

$$\mathbf{M} = \mathbf{M} \mathbf{Q} \mathbf{Q}^{\mathsf{T}} = \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^{\mathsf{T}} = \sum_{i} \lambda_{i} \mathbf{v}_{i} \mathbf{v}_{i}^{\mathsf{T}}$$



M = L: Properties of Graph Laplacian

We can assume **non-negative weights**: $w_{ij} \ge 0$.

L is symmetric

L positive semi-definite $\leftarrow \mathbf{f}^{\mathsf{T}}\mathbf{L}\mathbf{f} = \frac{1}{2}\sum_{i,j\leq N} w_{i,j}(f_i - f_j)^2$

Recall: If $\mathbf{Lf} = \lambda \mathbf{f}$ then λ is an **eigenvalue** (of the Laplacian).

The smallest eigenvalue of L is 0. Corresponding eigenvector: 1_N .

All eigenvalues are non-negative reals $0 = \lambda_1 \le \lambda_2 \le \cdots \le \lambda_N$.

Self-edges do not change the value of L.



Properties of Graph Laplacian

The multiplicity of eigenvalue 0 of ${\bf L}$ equals to the number of connected components. The eigenspace of 0 is spanned by the components' indicators.

Proof: If $(0, \mathbf{f})$ is an eigenpair then $0 = \frac{1}{2} \sum_{i,j \leq N} w_{i,j} (f_i - f_j)^2$. Therefore, \mathbf{f} is constant on each connected component. If there are k components, then \mathbf{L} is k-block-diagonal:

$$\mathbf{L} = \left[egin{array}{cccc} \mathbf{L}_1 & & & & \ & \mathbf{L}_2 & & & \ & & \ddots & & \ & & & \mathbf{L}_k \end{array}
ight]$$

For block-diagonal matrices: the spectrum is the union of the spectra of L_i (eigenvectors of L_i padded with zeros elsewhere).

For \mathbf{L}_i $(0, \mathbf{1}_{|V_i|})$ is an eigenpair, hence the claim.



Smoothness of the Function and Laplacian

- $\mathbf{f} = (f_1, \dots, f_N)^{\mathsf{T}}$: graph function
- ▶ Let $\mathbf{L} = \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^{\mathsf{T}}$ be the eigendecomposition of the Laplacian.
 - Diagonal matrix Λ whose diagonal entries are eigenvalues of L.
 - ► Columns of **Q** are eigenvectors of **L**.
 - Columns of Q form a basis.
- ightharpoonup lpha: Unique vector such that $\mathbf{Q}\alpha = \mathbf{f}$ Note: $\mathbf{Q}^{\mathsf{T}}\mathbf{f} = \alpha$

Smoothness of a graph function $S_G(\mathbf{f})$

$$S_{\mathcal{G}}(\mathbf{f}) = \mathbf{f}^{\mathsf{T}} \mathbf{L} \mathbf{f} = \mathbf{f}^{\mathsf{T}} \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^{\mathsf{T}} \mathbf{f} = \boldsymbol{\alpha}^{\mathsf{T}} \mathbf{\Lambda} \boldsymbol{\alpha} = \|\boldsymbol{\alpha}\|_{\mathbf{\Lambda}}^2 = \sum_{i=1}^{N} \lambda_i \alpha_i^2$$

Smoothness and regularization: Small value of

(a)
$$S_G(\mathbf{f})$$
 (b) Λ norm of α^* (c) α_i^* for large λ_i



Smoothness of the Function and Laplacian

$$S_G(\mathbf{f}) = \mathbf{f}^\mathsf{T} \mathbf{L} \mathbf{f} = \mathbf{f}^\mathsf{T} \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^\mathsf{T} \mathbf{f} = \alpha^\mathsf{T} \mathbf{\Lambda} \alpha = \|\alpha\|_{\mathbf{\Lambda}}^2 = \sum_{i=1}^N \lambda_i \alpha_i^2$$

Eigenvectors are graph functions too!

What is the smoothness of an eigenvector?

Spectral coordinates of eigenvector \mathbf{v}_k : $\mathbf{Q}^\mathsf{T}\mathbf{v}_k = \mathbf{e}_k$

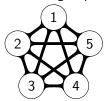
$$S_G(\mathbf{v}_k) = \mathbf{v}_k^{\mathsf{T}} \mathbf{L} \mathbf{v}_k = \mathbf{v}_k^{\mathsf{T}} \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^{\mathsf{T}} \mathbf{v}_k = \mathbf{e}_k^{\mathsf{T}} \mathbf{\Lambda} \mathbf{e}_k = \|\mathbf{e}_k\|_{\mathbf{\Lambda}}^2 = \sum_{i=1}^N \lambda_i (\mathbf{e}_k)_i^2 = \lambda_k$$

The smoothness of k-th eigenvector is the k-th eigenvalue.



Laplacian of the Complete Graph K_N

What is the eigenspectrum of L_{K_N} ?



$$\mathbf{L}_{\mathcal{K}_N} = \left(\begin{array}{ccccc} N-1 & -1 & -1 & -1 & -1 \\ -1 & N-1 & -1 & -1 & -1 \\ -1 & -1 & N-1 & -1 & -1 \\ -1 & -1 & -1 & N-1 & -1 \\ -1 & -1 & -1 & -1 & N-1 \end{array} \right)$$

From before: we know that $(0, \mathbf{1}_N)$ is an eigenpair.

If $\mathbf{v} \neq \mathbf{0}_N$ and $\mathbf{v} \perp \mathbf{1}_N \implies \sum_i \mathbf{v}_i = 0$. To get the other eigenvalues, we compute $(\mathbf{L}_{K_N} \mathbf{v})_1$ and divide by \mathbf{v}_1 (wlog $\mathbf{v}_1 \neq 0$).

$$(\mathsf{L}_{\mathcal{K}_{\mathcal{N}}}\mathsf{v})_1=(\mathcal{N}-1)\mathsf{v}_1-\sum_{i=2}^{\mathcal{N}}\mathsf{v}_i=\mathcal{N}\mathsf{v}_1.$$

What are the remaining eigenvalues/vectors?



Normalized Laplacians

$$\begin{split} \textbf{L}_{\textit{un}} &= \textbf{D} - \textbf{W} \\ \textbf{L}_{\textit{sym}} &= \textbf{D}^{-1/2} \textbf{L} \textbf{D}^{-1/2} = \textbf{I} - \textbf{D}^{-1/2} \textbf{W} \textbf{D}^{-1/2} \\ \textbf{L}_{\textit{rw}} &= \textbf{D}^{-1} \textbf{L} = \textbf{I} - \textbf{D}^{-1} \textbf{W} \end{split}$$

$$\mathbf{f}^{\mathsf{T}} \mathbf{L}_{sym} \mathbf{f} = \frac{1}{2} \sum_{i,j \leq N} w_{i,j} \left(\frac{f_i}{\sqrt{d_i}} - \frac{f_j}{\sqrt{d_j}} \right)^2$$

 (λ, \mathbf{u}) is an eigenpair for \mathbf{L}_{rw} iff $(\lambda, \mathbf{D}^{1/2}\mathbf{u})$ is an eigenpair for \mathbf{L}_{sym}



Normalized Laplacians

 \mathbf{L}_{sym} and \mathbf{L}_{rw} are PSD with non-negative real eigenvalues

$$0 = \lambda_1 \leq \lambda_2 \leq \lambda_3 \leq \cdots \leq \lambda_N$$

 (λ, \mathbf{u}) is an eigenpair for \mathbf{L}_{rw} iff (λ, \mathbf{u}) solve the generalized eigenproblem $\mathbf{L}\mathbf{u} = \lambda \mathbf{D}\mathbf{u}$.

 $(0, \mathbf{1}_N)$ is an eigenpair for \mathbf{L}_{rw} .

 $(0, \mathbf{D}^{1/2} \mathbf{1}_{N})$ is an eigenpair for \mathbf{L}_{sym} .

Multiplicity of eigenvalue 0 of \mathbf{L}_{rw} or \mathbf{L}_{sym} equals to the number of connected components.

Proof: As for L.



Laplacian and Random Walks on Undirected Graphs

- stochastic process: vertex-to-vertex jumping
- ▶ transition probability $v_i \rightarrow v_j$ is $p_{ij} = w_{ij}/d_i$

$$\blacktriangleright d_i \stackrel{\text{def}}{=} \sum_i w_{ij}$$

- ▶ transition matrix $\mathbf{P} = (p_{ii})_{ii} = \mathbf{D}^{-1}\mathbf{W}$ (notice $\mathbf{L}_{rw} = \mathbf{I} \mathbf{P}$)
- ▶ if *G* is connected and non-bipartite \rightarrow unique **stationary** distribution $\pi = (\pi_1, \pi_2, \pi_3, \dots, \pi_N)$ where $\pi_i = d_i/\text{vol}(V)$

$$ightharpoonup \operatorname{vol}(G) = \operatorname{vol}(V) = \operatorname{vol}(\mathbf{W}) \stackrel{\text{def}}{=} \sum_i d_i = \sum_{i,j} w_{ij}$$

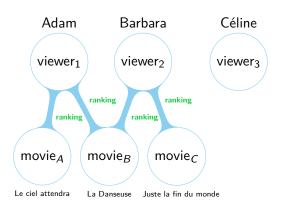
 $m \pi = \frac{\mathbf{1}^\mathsf{T} \mathbf{W}}{\mathrm{vol}(\mathbf{W})}$ verifies $\pi \mathbf{P} = \pi$ as:

$$\pi \mathbf{P} = \frac{\mathbf{1}^\mathsf{T} \mathbf{W} \mathbf{P}}{\mathrm{vol}(\mathbf{W})} = \frac{\mathbf{1}^\mathsf{T} \mathbf{D} \mathbf{P}}{\mathrm{vol}(\mathbf{W})} = \frac{\mathbf{1}^\mathsf{T} \mathbf{D} \mathbf{D}^{-1} \mathbf{W}}{\mathrm{vol}(\mathbf{W})} = \frac{\mathbf{1}^\mathsf{T} \mathbf{W}}{\mathrm{vol}(\mathbf{W})} = \pi$$



Use of Laplacians: Movie recommendation

How to do movie recommendation on a bipartite graph?



Question: Do we recommend <u>Juste la fin du monde</u> to Adam? Let's compute some score(v, m)!



Use of Laplacians: Movie recommendation

How to compute the score(v, m)? Using some graph distance!

Idea₁: maximally weighted path

$$\operatorname{score}(v, m) = \max_{v \neq m} \operatorname{weight}(P) = \max_{v \neq m} \sum_{e \in P} \operatorname{ranking}(e)$$

Idea₂: change the path weight

 $score_2(v, m) = \max_{vPm} weight_2(P) = \max_{vPm} \min_{e \in P} ranking(e)$

Idea₃: consider everything

 $score_3(v, m) = max flow from m to v$

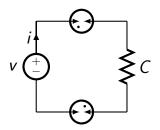


Laplacians and Resistive Networks

How to compute the score(v, m)?

Idea₄: view edges as conductors

 $score_4(v, m) = effective resistance between m and v$



 $C \equiv \text{conductance}$

 $R \equiv \text{resistance}$

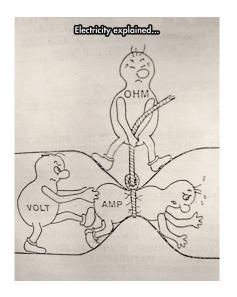
 $i \equiv \text{current}$

 $V \equiv \text{voltage}$

$$C = \frac{1}{R}$$
 $i = CV = \frac{V}{R}$



Resistive Networks: Some high-school physics





Resistive Networks

resistors in series

$$R = R_1 + \dots + R_n$$
 $C = \frac{1}{\frac{1}{C_1} + \dots + \frac{1}{C_N}}$ $i = \frac{V}{R}$

conductors in parallel

$$C = C_1 + \cdots + C_N$$
 $i = VC$

Effective Resistance on a graph

Take two nodes: $a \neq b$. Let V_{ab} be the voltage between them and i_{ab} the current between them. Define $R_{ab} = \frac{V_{ab}}{i_{ab}}$ and $C_{ab} = \frac{1}{R_{ab}}$.

We treat the entire graph as a resistor!



Resistive Networks: Optional Homework (ungraded)

Show that R_{ab} is a metric space.

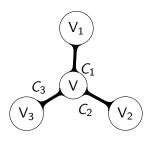
- 1. $R_{ab} > 0$
- 2. $R_{ab} = 0$ iff a = b
- 3. $R_{ab} = R_{ba}$
- 4. $R_{ac} \leq R_{ab} + R_{bc}$

The effective resistance is a distance!



How to compute effective resistance?

Kirchhoff's Law \equiv flow in = flow out



$$V = \frac{C_1}{C}V_1 + \frac{C_2}{C}V_2 + \frac{C_3}{C}V_3$$
 (convex combination) residual current = $CV - C_1V_1 - C_2V_2 - C_3V_3$ Kirchhoff says: This is zero! There is no residual current!



Resistors: Where is the link with the Laplacian?

General case of the previous! $d_i = \sum_j c_{ij} = \text{sum of conductances}$

$$\mathbf{L}_{ij} = egin{cases} d_i & ext{if } i = j, \ -c_{ij} & ext{if } (i,j) \in E, \ 0 & ext{otherwise}. \end{cases}$$

 $\mathbf{v} = \mathbf{voltage}$ setting of the nodes on graph.

 $(\mathbf{L}\mathbf{v})_i = \text{residual current at } \mathbf{v}_i - \mathbf{v}_i = \mathbf{v}_i$

Use: setting voltages and getting the current

Inverting ≡ injecting current and getting the voltages

The net injected has to be zero - Kirchhoff's Law.



Resistors and the Laplacian: Finding R_{ab}

Let's calculate R_{1N} to get the movie recommendation score!

$$\mathbf{L} \begin{pmatrix} 0 \\ v_2 \\ \vdots \\ v_{n-1} \\ 1 \end{pmatrix} = \begin{pmatrix} i \\ 0 \\ \vdots \\ 0 \\ -i \end{pmatrix}$$

$$i = \frac{V}{R} \qquad V = 1 \qquad R = \frac{1}{i}$$

$$\text{Return } R_{1N} = \frac{1}{i}$$

Doyle and Snell: Random Walks and Electric Networks https://math.dartmouth.edu/~doyle/docs/walks/walks.pdf



Resistors and the Laplacian: Finding R_{1N}

$$\mathbf{L}\mathbf{v} = (i, 0, \dots, -i)^{\mathsf{T}} \equiv \mathbf{boundary} \ \mathbf{valued} \ \mathbf{problem}$$

For R_{1N}

 V_1 and V_N are the **boundary**

 (v_1, v_2, \dots, v_N) is harmonic:

 $V_i \in \mathbf{interior}$ (not boundary)

 V_i is a convex combination of its neighbors



Resistors and the Laplacian: Finding R_{1n}

From the properties of electric networks (cf. Doyle and Snell) we inherit the useful properties of the Laplacians!

Example: Semi-Supervised Learning Using Gaussian Fields and Harmonic Functions (later in the course)

Maximum Principle

If $\mathbf{f} = \mathbf{v}$ is harmonic then min and max are on the boundary.

Uniqueness Principle

If \mathbf{f} and \mathbf{g} are harmonic with the same boundary then $\mathbf{f} = \mathbf{g}$



Resistors and the Laplacian: Finding R_{1N}

Alternative method to calculate R_{1N} :

$$\mathbf{L}\mathbf{v} = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \\ -1 \end{pmatrix} \stackrel{\mathrm{def}}{=} \mathbf{i}_{\mathrm{ext}} \quad \mathrm{Return} \quad R_{1N} = v_1 - v_N$$
 Why?

Question: Does **v** exist? **L** does not have an inverse :(.

Not unique: 1 in the nullspace of $\mathbf{L} : \mathbf{L}(\mathbf{v} + c\mathbf{1}) = \mathbf{L}\mathbf{v} + c\mathbf{L}\mathbf{1} = \mathbf{L}\mathbf{v}$

Moore-Penrose pseudo-inverse solves LS

Solution: Instead of $\mathbf{v} = \mathbf{L}^{-1}\mathbf{i}_{\mathrm{ext}}$ we take $\mathbf{v} = \mathbf{L}^{+}\mathbf{i}_{\mathrm{ext}}$

We get: $R_{1N} = v_1 - v_N = \mathbf{i}_{\text{ext}}^\mathsf{T} \mathbf{v} = \mathbf{i}_{\text{ext}}^\mathsf{T} \mathbf{L}^+ \mathbf{i}_{\text{ext}}$.

Notice: We can reuse L⁺ to get resistances for any pair of nodes!



What? A pseudo-inverse?

Eigendecomposition of the Laplacian:

$$\mathbf{L} = \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^{\mathsf{T}} = \sum_{i=1}^{N} \lambda_{i} \mathbf{q}_{i} \mathbf{q}_{i}^{\mathsf{T}} = \sum_{i=2}^{N} \lambda_{i} \mathbf{q}_{i} \mathbf{q}_{i}^{\mathsf{T}}$$

Pseudo-inverse of the Laplacian:

$$\mathbf{L}^{+} = \mathbf{Q} \mathbf{\Lambda}^{+} \mathbf{Q}^{\mathsf{T}} = \sum_{i=2}^{N} \frac{1}{\lambda_{i}} \mathbf{q}_{i} \mathbf{q}_{i}^{\mathsf{T}}$$

Moore-Penrose pseudo-inverse solves a least squares problem:

$$\mathbf{v} = \mathop{\mathsf{arg\,min}}_{\mathbf{x}} \left\| \mathbf{L} \mathbf{x} - \mathbf{i}_{\mathrm{ext}} \right\|_2 = \mathbf{L}^+ \mathbf{i}_{\mathrm{ext}}$$



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