# Learning Good Edit Similarities with Generalization Guarantees

#### Aurélien Bellet<sup>1</sup> Amaury Habrard<sup>2</sup> Marc Sebban<sup>1</sup>

<sup>1</sup>Laboratoire Hubert Curien, UMR CNRS 5516, Université de Saint-Etienne {aurelien.bellet,marc.sebban}@univ-st-etienne.fr

<sup>2</sup>Laboratoire d'Informatique Fondamentale, UMR CNRS 6166, Aix-Marseille Université amaury.habrard@lif.univ-mrs.fr

#### ECML PKDD '11, Athens

# Introduction: Similarity Learning

Bellet, Habrard and Sebban (LaHC, LIF)

# Similarity functions in classification

- Common approach in supervised classification: learn to classify objects using a **pairwise similarity (or distance) function**.
- Successful examples: k-Nearest Neighbor (k-NN), Support Vector Machines (SVM).
- Best way to get a "good" similarity function for a specific task: learn it from data!

# Similarity learning

#### Similarity learning overview

Learning a similarity function K(x, x') implying a new instance space where the performance of a given algorithm is improved.



#### Very popular approach for numerical data

Learn the transformation matrix A of a Mahalanobis distance:

$$d(x,y) = (x-y)A^{T}A(x-y)$$

Bellet, Habrard and Sebban (LaHC, LIF)

# Goals of our work

#### Goals of our work

- Learn a similarity function for string classification;
- Which is guaranteed to generalize well to new examples;
- and provably induce low-error classifiers for the task at hand.

#### Building block

Make use of the theory of learning with  $(\epsilon, \gamma, \tau)$ -good similarity functions (Balcan et al.).

# $(\epsilon, \gamma, \tau)$ -good similarity functions

# Definition

Balcan et al. (2006, 2008) wanted a definition of good similarity function that

- talks in terms of natural, direct properties;
- includes the usual notion of good kernel, without PSD requirement;
- provides guarantees for learning.

#### Definition (Balcan et al., 2008)

A similarity function  $K \in [-1, 1]$  is an  $(\epsilon, \gamma, \tau)$ -good similarity function for a learning problem P if there exists an indicator function R(x) defining a set of "reasonable points" such that the following conditions hold:

• A  $1 - \epsilon$  probability mass of examples  $(x, \ell)$  satisfy:

$$\mathbf{E}_{(x',\ell')\sim P}\left[\ell\ell' K(x,x') | R(x')\right] \geq \gamma$$

$$Pr_{x'}[R(x')] \geq \tau.$$

Bellet, Habrard and Sebban (LaHC, LIF)

 $\epsilon, \gamma, \tau \in [0, 1]$ 

 $(\epsilon, \gamma, \tau)$ -good similarity functions Int

Intuition behind the definition

# Intuition behind the definition



 $\mathcal{K}(x,x') = -\|x-x'\|_2$  is good with  $\epsilon = 0$ ,  $\gamma = 0.03$ ,  $\tau = 3/8$ 

 $(\epsilon, \gamma, \tau)$ -good similarity functions Int

Intuition behind the definition

# Intuition behind the definition



 $\mathcal{K}(x,x') = -\|x-x'\|_2$  is good with  $\epsilon = 1/8$ ,  $\gamma = 0.12$ ,  $\tau = 3/8$ 

# Implications for learning

#### Strategy

Each example is mapped to the space of "the similarity scores with the reasonable points".



# Implications for learning

#### Theorem (Balcan et al., 2008)

Given K is  $(\epsilon, \gamma, \tau)$ -good, there exists a linear separator  $\alpha$  in the above-defined projection space that has error close to  $\epsilon$  at margin  $\gamma$ .



# Learning rule

#### Learning the separator $\alpha$ with a linear program

$$\min_{\boldsymbol{\alpha}} \sum_{i=1}^{d_l} \left[ 1 - \sum_{j=1}^{d_u} \alpha_j \ell_i \mathcal{K}(\boldsymbol{x}_i, \boldsymbol{x}_j') \right]_+ + \lambda \|\boldsymbol{\alpha}\|_1$$

where 
$$[1 - c]_+ = max(1 - c, 0)$$
 is the hinge-loss.

#### Automatic selection of reasonable points

The best set of reasonable points is automatically chosen among the examples thanks to the L<sub>1</sub>-regularization on  $\alpha$ .

# L<sub>1</sub>-norm and Sparsity

• Why does L<sub>1</sub>-norm constraint/regularization induce sparsity? Geometric interpretation:



Examples corresponding to non-zero coordinates in  $\alpha$  are the • reasonable points.

# Learning good edit similarities

Bellet, Habrard and Sebban (LaHC, LIF)

#### Motivations

# Motivations for our work

Two main motivations for our work:

#### Motivation 1

The definition of  $(\epsilon, \gamma, \tau)$ -good similarity function gives us **a natural** objective to optimize:

$$\mathsf{E}_{(x',\ell')\sim P}\left[\ell\ell' \mathcal{K}(x,x')|R(x')\right] \geq \gamma.$$

If we satisfy this, then we can find a low-error classifier for the task.

#### Motivation 2

Similarity functions for **structured data** (strings, trees...) are often **not PSD**. Not so easy to use in SVM.

# The string edit distance

Standard (Levenshtein) edit distance  $e_L$  between two strings x and y: minimum number of operations to transform x into y. Allowable operations are insertion, deletion and substitution of symbols.

#### Example 1

$$e_L(abb, aa) = C(b, a) + C(b, \$) = 1 + 1 = 2$$

Generalized version  $e_C$ : use a **cost** for each operation.

#### Example 2



$$\Rightarrow e_{\mathcal{C}}(\textit{abb},\textit{aa}) = \mathcal{C}(\textit{b},\$) + \mathcal{C}(\textit{b},\$) + \mathcal{C}(\$,\textit{a}) = 1$$

#### \$: empty symbol

Bellet, Habrard and Sebban (LaHC, LIF)

# A feel of the state-of-the-art in edit cost learning

There exists a decent amount of literature on **learning edit costs** (or probabilities) **from data**. See Ristad & Yianilos (1998), Bilenko & Mooney (2003), Oncina & Sebban (2006), Takasu (2009)...

#### Drawbacks of the state-of-the-art

- most of them use an iterative procedure, which can be costly.
- they often make use of **positive pairs only** (i.e., moving examples of the same class "closer" together). What about negative pairs?
- above all, they are **not learned to be**  $(\epsilon, \gamma, \tau)$ -good.
  - $\hookrightarrow$  they are not guaranteed to perform well for the task at hand.

# Our edit similarity function

An iterative approach is usually needed because **the optimal edit script** (= best sequence of operations) **depends on the edit costs**.

 $\hookrightarrow$  Solution: define a different type of edit function!

Definition of  $e_G$ 

$$e_G(x,x') = \sum_{0 \le i,j \le A} C_{i,j} \times \#_{i,j}(x,x')$$

where A is the size of the alphabet, C the edit cost matrix and  $\#_{i,j}(x, x')$  the number of times the operation (i, j) appears in the Levenshtein script. We will optimize:

### Definition of $K_G$

$$K_G(x, x') = 2e^{-e_G(x, x')} - 1 \in [-1, 1]$$

# Optimize the goodness

Optimizing the  $(\epsilon, \gamma, \tau)$ -goodness of  $K_G$  is difficult for two reasons:

- Optimizing the definition directly would result in nonconvexity (summing/subtracting up exponential terms).
- We do not know the set of reasonable points R at this point.

#### Solution to the first issue

Optimize a criterion that bounds goodness:

$$\mathbf{E}_{(x,l)}\left[\mathbf{E}_{(x',\ell')}\left[\left[1-\ell\ell'K_G(x,x')/\gamma\right]_+|R(x')\right]\right] \leq \epsilon'.$$

**Interpretation**: goodness is required with respect to each reasonable point (instead of considering the average similarity to these points).

# Optimize the goodness ctd

What about the second issue?

- Taking all points as reasonable is **not** a good idea (defines an overconstrained problem).
- Reasonable points can be seen as good representatives of a subset of the class examples.

#### Solution to second issue

Use an indicator matching function  $f_{land}$ :  $T \times S_L \rightarrow \{0, 1\}$  that associates each training example in T with  $N_L$  examples in  $S_L$ .

In our experiments, we matched each example with its P nearest-neighbors of same class and its P farthest-neighbor of opposite class in T using the Levenshtein distance.

# Convex formulation of the problem

#### Recall the underlying idea

Moving closer pairs of the same class and further those of opposite class.

#### Our convex formulation

$$\min_{\substack{C,B_1,B_2 \\ i \leq j \leq N_T, \\ f_{land}(x_i,x_j') = 1}} \frac{1}{V(C,z_i,z_j')} + \beta \|C\|^2 \\ s.t. \quad V(C,z_i,z_j') = \begin{cases} [B1 - e_G(x_i,x_j')]_+ & \text{if } \ell_i \neq \ell_j' \\ [e_G(x_i,x_j') - B2]_+ & \text{if } \ell_i = \ell_j' \\ B_1 \geq -\log(\frac{1}{2}), & 0 \leq B_2 \leq -\log(\frac{1}{2}), & B_1 - B_2 = \eta_\gamma \\ C_{i,j} \geq 0, & 0 \leq i,j \leq A \end{cases}$$

Parameters:

- $\beta$ : regularization parameter on the edit costs.
- $\eta_{\gamma}$ : the "desired margin".

Bellet, Habrard and Sebban (LaHC, LIF)

# Learning guarantees

Bounding the true error of an edit model C

$$L(C) = \mathbf{E}_{z_k, z'_j}[V(C, z_k, z'_j)]$$

#### Uniform stability [Bousquet et al. 02, Jin et al. 09]

Idea: study the impact of a small change in the training sample.

$$\forall (T, z), |T| = N_T, \forall i, \sup_{z_1, z_2} |V(C_T, z_1, z_2) - V(C_{T^{i, z}}, z_1, z_2)| \le \frac{\kappa}{N_T}$$

 $T^{i,z}$  set obtained by replacing  $z_i \in T$  by z

 $\hookrightarrow \mathsf{Generalization} \ \mathsf{bound}$ 

# Convergence and learning guarantees

Theorem: Algorithm has a uniform stability in  $\kappa/N_T$ 

$$\kappa = \frac{2(2+\alpha)W^2}{\beta\alpha}$$

W is a bound on the string sizes;  $0 \le \alpha \le 1$  such that  $N_L = \alpha N_T$ .

Theorem: Generalization bound - Convergence in  $O(\sqrt{1/N_T})$ 

$$L(C) < \hat{L}(C) + 2rac{\kappa}{N_T} + (2\kappa + B)\sqrt{rac{\ln(2/\delta)}{2N_T}}$$

 $\hat{L}(C)$ : empirical error on learning sample.

#### $\hookrightarrow$ Independence from the size of the alphabet

## Convergence rate: accuracy

Task: **classify words** as either French or English (top words lists from Wiktionary).



24 / 26

# Classification performance: sparsity



# Conclusions

#### Recap

- We made use of the framework of Balcan et al. to create a **novel**, efficient way to learn string similarities.
- The resulting similarities provably **generalize well** to new examples and **induce low-error classifiers** for the task at hand.

#### Future work

- Adapt our method to tree edit cost learning (straightforward).
- Learn **other types of similarities** (e.g. numerical distances such as Mahalanobis distance).