BETTER PRIVACY GUARANTEES FOR DECENTRALIZED FEDERATED LEARNING

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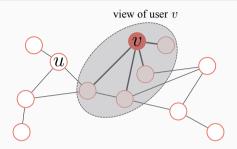
Workshop FL-Day - Decentralized Federated Learning: Approaches and Challenges January 10, 2023

DECENTRALIZED ALGORITHMS: GOOD FOR PRIVACY?



- In decentralized algorithms, such as decentralized SGD [Lian et al., 2017] [Koloskova et al., 2020], users communicate along the edges of a graph
- These algorithms are increasingly popular in machine learning due to their scalability

DECENTRALIZED ALGORITHMS: GOOD FOR PRIVACY?



- In decentralized algorithms, such as decentralized SGD [Lian et al., 2017] [Koloskova et al., 2020], users communicate along the edges of a graph
- These algorithms are increasingly popular in machine learning due to their scalability
- Folklore belief: "Decentralized algorithms are good for privacy because users have a limited view of the system"
- Question: is this claim really true? can we formalize and quantify these gains? Yes!

1. Background: Differential Privacy & DP-SGD

2. A relaxation of local DP for decentralized algorithms

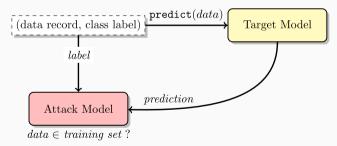
3. Private random walk-based decentralized SGD

4. Private gossip-based decentralized SGD

5. Conclusion & Perspectives

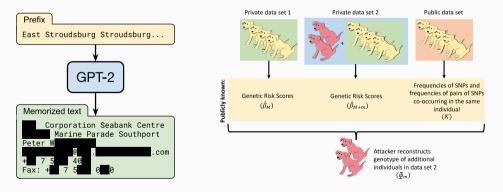
BACKGROUND: DIFFERENTIAL PRIVACY & DP-SGD

- ML models are susceptible to various attacks on data privacy
- Membership inference attack: infer whether a known individual data point was present in the training set
- For instance, one can exploit overconfidence in model predictions [Shokri et al., 2017] [Carlini et al., 2022]

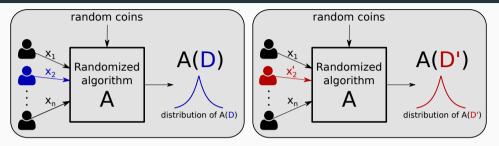


PRIVACY ISSUES IN MACHINE LEARNING

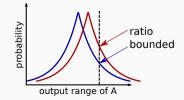
- · Reconstruction attack: extract training data points from the model
- For instance, one can extract sensitive text from large language models [Carlini et al., 2021] or run differencing attacks on ML models [Paige et al., 2020]



DIFFERENTIAL PRIVACY



- Neighboring datasets $\mathcal{D} = \{x_1, x_2, \dots, x_n\}$ and $\mathcal{D}' = \{x_1, x'_2, x_3, \dots, x_n\}$
- **Requirement**: $\mathcal{A}(\mathcal{D})$ and $\mathcal{A}(\mathcal{D}')$ should have "similar" distributions



Definition (Rényi Differential Privacy [Mironov, 2017])

An algorithm \mathcal{A} satisfies (α, ϵ) -Rényi Differential Privacy (RDP) for $\alpha > 1$ and $\epsilon > 0$ if for all pairs of neighboring datasets $\mathcal{D} \sim \mathcal{D}'$:

$$D_{\alpha}\left(\mathcal{A}(\mathcal{D})||\mathcal{A}(\mathcal{D}')\right) \leq \epsilon$$
, (1)

where for two r.v. X, Y with densities $\mu_X, \mu_Y, D_{\alpha}(X || Y)$ is the Rényi divergence of order α :

$$D_{\alpha}(X || Y) = \frac{1}{\alpha - 1} \ln \int \left(\frac{\mu_X(z)}{\mu_Y(z)}\right)^{\alpha} \mu_Y(z) dz$$

• Conversion to standard (ϵ, δ) -DP: (α, ϵ) -RDP implies $(\epsilon + \frac{\ln(1/\delta)}{\alpha-1}, \delta)$ -DP for any $\delta \in (0, 1)$

PROPERTIES OF RDP

- RDP is robust to auxiliary knowledge, as seen by its Bayesian interpretation:
 - \cdot Consider an adversary who seeks to infer whether the dataset is ${\cal D}$ or ${\cal D}'$
 - The adversary has prior knowledge p and observes $X \sim \mathcal{A}(\mathcal{D})$
 - Let the r.v. $R_{prior} = \frac{p(\mathcal{D}')}{p(\mathcal{D})}$ and $R_{post} = \frac{p(\mathcal{D}'|X)}{p(\mathcal{D}|X)} = \frac{p(X|\mathcal{D}')p(\mathcal{D}')}{p(X|\mathcal{D})p(\mathcal{D})}$ for $X \sim \mathcal{A}(\mathcal{D})$
 - RDP bounds the α -th moment of $\frac{R_{\text{post}}}{R_{\text{refer}}}$ (for $\alpha \to \infty$, we recover "pure" ϵ -DP)
 - "The adversary does not know much more after observing the output of the algorithm"
- Immunity to post-processing: for any g, if $\mathcal{A}(\cdot)$ is (α, ϵ) -RDP, then so is $g(\mathcal{A}(\cdot))$
- Composition: if A_1 is (α, ϵ_1) -RDP and A_2 is (α, ϵ_2) -RDP, then $A = (A_1, A_2)$ is $(\alpha, \epsilon_1 + \epsilon_2)$ -RDP \rightarrow simpler and tighter than composition for (ϵ, δ) -DP

- Consider f taking as input a dataset and returning a p-dimensional real vector
- Denote its sensitivity by $\Delta = \max_{\mathcal{D} \sim \mathcal{D}'} \|f(\mathcal{D}) f(\mathcal{D}')\|_2$

Theorem (Gaussian mechanism)

Let $\sigma > 0$. The algorithm $\mathcal{A}(\cdot) = f(\cdot) + \mathcal{N}(0, \sigma^2 \Delta^2)$ satisfies $(\alpha, \frac{\alpha}{2\sigma^2})$ -RDP for any $\alpha > 1$.

Theorem (Subsampled Gaussian mechanism, informal)

If \mathcal{A} is executed on a random fraction q of \mathcal{D} , then it satisfies $(\alpha, \frac{q^2 \alpha}{2\sigma^2})$ -RDP.

- DP induces a privacy-utility trade-off, here in terms of the variance of the estimate
- Random subsampling amplifies privacy guarantees

- A trusted curator wants to privately release a model trained on data $\mathcal{D} = \{(x_i, y_i)\}_{i=1}^n$
- We focus here on approximately solving an Empirical Risk Minimization (ERM) problem under a DP constraint:

$$\min_{\theta \in \mathbb{R}^p} \Big\{ F(\theta; \mathcal{D}) := \frac{1}{n} \sum_{i=1}^n \ell(\theta; x_i, y_i) \Big\}, \quad \text{where loss } \ell \text{ is differentiable in } \theta$$

• Note: in some cases, DP implies generalization [Bassily et al., 2016, Jung et al., 2021]

Algorithm Differentially Private SGD (DP-SGD) [Bassily et al., 2014, Abadi et al., 2016]

Initialize $\theta^{(0)} \in \mathbb{R}^p$ (must be independent of \mathcal{D}) for t = 0, ..., T - 1 do Pick $i_t \in \{1, ..., n\}$ uniformly at random $\eta^{(t)} \leftarrow (\eta_1^{(t)}, ..., \eta_p^{(t)}) \in \mathbb{R}^p$ where each $\eta_j^{(t)} \sim \mathcal{N}(0, \sigma^2 \Delta^2)$ $\theta^{(t+1)} \leftarrow \theta^{(t)} - \gamma^{(t)} (\nabla \ell(\theta^{(t)}; x_{i_t}, y_{i_t}) + \eta^{(t)})$ Return $\theta^{(T)}$

• The sensitivity $\Delta = \sup_{\theta} \sup_{x,y,x',y'} \|\nabla \ell(\theta; x, y) - \nabla \ell(\theta; x', y')\|$ can be controlled by assuming $\ell(\cdot; x, y)$ Lipschitz for all x, y, or using gradient clipping [Abadi et al., 2016]

- Utility analysis: same as non-private SGD (with additional noise due to privacy)
- Privacy analysis: DP-SGD is $(\alpha, \frac{\alpha T}{2n^2\sigma^2})$ by subsampled Gaussian mechanism + composition over T iterations
- Setting σ^2 to satisfy (ϵ, δ) -DP and choosing *T* to balance optimization and privacy errors, we get the following suboptimality gap:

Convex, Lipschitz, smooth loss

$$\tilde{O}\left(\frac{\sqrt{p}\ln(1/\delta)}{n\epsilon}\right)$$

Convex, Lipschitz, smooth loss, strongly convex F

 $\left(\frac{p\ln(1/\delta)}{n^2\epsilon^2}\right)$

• This is optimal [Bassily et al., 2014]: cannot do better without additional assumptions

REMOVING THE TRUSTED CURATOR: LOCAL DP

- So far we considered the central DP model, which relies on a trusted curator to collect and process raw data \rightarrow the output $\mathcal{A}(\mathcal{D})$ is only the final result
- Central DP is good for utility but is an unrealistic trust model in applications where many parties contribute sensitive data, as in federated learning
- Instead we can consider for local DP, where each party must locally randomize its contributions \rightarrow the output of $\mathcal{A}(\mathcal{D})$ consists of all messages sent by all parties
- Unfortunately local DP induces a large cost in utility: for averaging *n* private *p*-dimensional values in ball of radius Δ under (α, ϵ)-RDP, we have

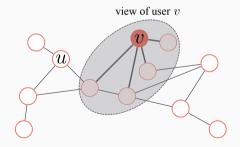
$$\mathbb{E}[\|x^{\text{out}} - \bar{x}\|^2] = \Theta\left(\frac{\alpha p \Delta^2}{n\epsilon}\right) \text{ for local DP}, \quad \text{and} \quad \mathbb{E}[\|x^{\text{out}} - \bar{x}\|^2] = \Theta\left(\frac{\alpha p \Delta^2}{n^2\epsilon}\right) \text{ for central DP}$$

 \rightarrow study intermediate models allowing better utility without relying on trusted parties

A RELAXATION OF LOCAL DP FOR DECENTRALIZED ALGORITHMS

DECENTRALIZED ALGORITHMS

- A connected graph $G = (\mathcal{V}, \mathcal{E})$ on a set of $|\mathcal{V}| = n$ users (nodes)
- Each user $v \in \mathcal{V}$ holds a local dataset \mathcal{D}_v
- \cdot A decentralized algorithm relies only on communication along the edges ${\mathcal E}$ of G
- Each user v thus has a limited view: it only observes the messages that it receives



• We want to use this to prove stronger privacy guarantees than under local DP

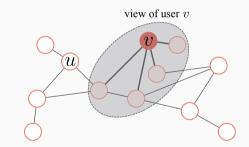
NETWORK DIFFERENTIAL PRIVACY

- · Let \mathcal{O}_v be the set of messages sent and received by party v
- Denote by $\mathcal{D} \sim_u \mathcal{D}'$ two datasets $\mathcal{D} = (\mathcal{D}_1, \dots, \mathcal{D}_u, \dots, \mathcal{D}_n)$ and $\mathcal{D}' = (\mathcal{D}_1, \dots, \mathcal{D}'_u, \dots, \mathcal{D}_n)$ that differ only in the local dataset of user u

Definition (Network DP [Cyffers and Bellet, 2022])

An algorithm \mathcal{A} satisfies (α, ϵ) -Network DP (NDP) if for all pairs of distinct users $u, v \in \mathcal{V}$ and neighboring datasets $\mathcal{D} \sim_u \mathcal{D}'$:

 $D_{lpha}ig(\mathcal{O}_{\scriptscriptstyle V}(\mathcal{A}(\mathcal{D}))\,||\,\mathcal{O}_{\scriptscriptstyle V}(\mathcal{A}(\mathcal{D}'))ig)\leq\epsilon\,.$



• This is a relaxation of local DP: if \mathcal{O}_v contains the full transcript of messages, then network DP boils down to local DP

• We will also consider privacy guarantees that are specific to each pair of nodes, rather than uniform over all pairs

Definition (Pairwise Network DP [Cyffers et al., 2022])

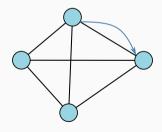
For $f: \mathcal{V} \times \mathcal{V} \to \mathbb{R}^+$, an algorithm \mathcal{A} satisfies (α, f) -Pairwise Network DP (PNDP) if for all pairs of distinct users $u, v \in \mathcal{V}$ and neighboring datasets $\mathcal{D} \sim_u \mathcal{D}'$:

$$D_{\alpha}(\mathcal{O}_{\mathsf{V}}(\mathcal{A}(\mathcal{D})) || \mathcal{O}_{\mathsf{V}}(\mathcal{A}(\mathcal{D}'))) \leq f(u, \mathbf{v}).$$
⁽²⁾

- For comparison with central and local DP baselines, we will report the mean privacy loss $\overline{e}_{v} = \frac{1}{n} \sum_{u \in \mathcal{V} \setminus \{v\}} f(u, v)$ under the constraint $\overline{e} = \max_{v \in \mathcal{V}} \overline{e}_{v} \leq \epsilon$
- Note: $\overline{\varepsilon}_{v}$ is not a proper privacy guarantee (we simply use it to summarize our gains)

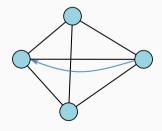
Private random walk-based decentralized SGD

- Consider the standard objective $F(\theta; D) = \frac{1}{n} \sum_{v=1}^{n} F_v(\theta; D_v)$
- We consider a decentralized SGD algorithm where the model is updated sequentially by following a random walk, aka incremental gradient [Johansson et al., 2009]
- We focus here on the complete graph



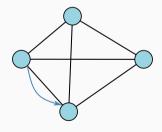
AlgorithmPrivate random walk-based SGD [Cyffers and Bellet, 2022]Initialize $\theta \in \mathbb{R}^p$ for t = 1 to T doDraw random user $v \sim \mathcal{U}(1, \dots, n)$ $\eta = [\eta_1, \dots, \eta_p]$, where each $\eta_j \sim \mathcal{N}(0, \sigma^2 \Delta^2)$ $\theta \leftarrow \theta - \gamma [\nabla_{\theta} F_v(\theta; \mathcal{D}_v) + \eta]$ return θ

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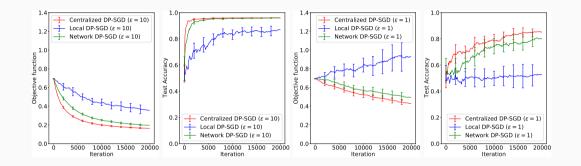


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Theorem ([Cyffers and Bellet, 2022], informal)

Let $F_1(\cdot; \mathcal{D}_1), \ldots, F_n(\cdot; \mathcal{D}_n)$ be convex and smooth. Given $\alpha > 1$, $\epsilon > 0$, let $T = \tilde{\Omega}(n^2)$ and σ^2 be such that private random walk-based decentralized SGD on the complete graph satisfies (α, ϵ) -local RDP. Then the algorithm also satisfies $(\alpha, \frac{\ln^2 n}{n}\epsilon)$ -network DP.

- In other words, accounting for the limited view in decentralized algorithms allows to recover the privacy-utility trade-off of DP-SGD under central DP! (up to a log factor)
- Note: for $T = o(n^2)$, the amplification effect is still strong and can be computed numerically, see [Cyffers and Bellet, 2022]
- Utility analysis: same as DP-SGD!
- Privacy analysis: leverages privacy amplification by iteration [Feldman et al., 2018] and exploits the randomness of the walk through "weak convexity" of Rényi divergence



• Numerical results are consistent with our theory: network DP-SGD significantly amplifies privacy guarantees compared to local DP-SGD

Private gossip-based decentralized SGD

- Random walk-based SGD is sequential (no parallel computation)
- A popular parallel alternative is gossip-based decentralized SGD [Lian et al., 2017] [Koloskova et al., 2020], which builds upon gossip averaging [Boyd et al., 2006]
- A gossip matrix over the graph $G = (\mathcal{V}, \mathcal{E})$ is a matrix $W \in \mathbb{R}^{n \times n}$ which:
 - is symmetric with nonnegative entries
 - \cdot is stochastic, i.e., W1 = 1
 - for any $v, w \in \mathcal{V}$, $W_{v,w} > 0$ implies $\{v, w\} \in \mathcal{E}$ or v = w

Algorithm GOSSIP_AVERAGING $(\{x_v\}_{v \in \mathcal{V}}, W, K)$ [Boyd et al., 2006]

for all nodes v in parallel do

 $x_v^0 \leftarrow x_v$

for *k* = 0 to *K* − 1 **do**

for all nodes v in parallel do

 $\begin{array}{l} x_v^{k+1} \leftarrow \sum_{w \in \mathcal{N}_v} W_{v,w} x_w^k, \quad \text{where } \mathcal{N}_v = \{w : W_{v,w} > 0\} \\ \text{return } x_1^K, \ldots, x_n^K \end{array}$

• Consider again $F(\theta; \mathcal{D}) = \frac{1}{n} \sum_{\nu=1}^{n} F_{\nu}(\theta; \mathcal{D}_{\nu})$ with $F_{\nu}(\theta; \mathcal{D}_{\nu}) = \frac{1}{|\mathcal{D}_{\nu}|} \sum_{(x_{\nu}, y_{\nu}) \in \mathcal{D}_{\nu}} \ell(\theta; x_{\nu}, y_{\nu})$

Algorithm Gossip-based decentralized SGD [Lian et al., 2017, Koloskova et al., 2020]

Initialize $\theta_1^{(0)}, \ldots, \theta_n^{(0)} \in \mathbb{R}^p$ for t = 0 to T - 1 do for all nodes v in parallel do $\hat{\theta}_v^t \leftarrow \theta_v^t - \gamma \nabla_{\theta} \ell(\theta_v^t; x_v^t, y_v^t)$ where $(x_v^t, y_v^t) \sim \mathcal{D}_v$ $\theta_v^{t+1} \leftarrow \text{GOSSIP}_{\text{AVERAGING}}(\{\hat{\theta}_v^t\}_{v \in \mathcal{V}}, W, K)$ return $\theta_1^T, \ldots, \theta_n^T$

• Note: to improve the dependence on the topology in the convergence rate we actually use accelerated gossip [Berthier et al., 2020]

• To make the algorithm private, we simply add Gaussian noise before gossiping

Algorithm PRIVATE_GOSSIP_AVERAGING($\{x_v\}_{v \in \mathcal{V}}, W, K, \sigma^2$)

for all nodes v in parallel do

 $\tilde{x}_{v}^{V} \leftarrow x_{v} + \eta_{v}$ where $\eta_{v} \sim \mathcal{N}(0, \sigma^{2})$ $x_{1}^{K}, \dots, x_{n}^{K} \leftarrow \text{GOSSIP}_{A} \text{VERAGING}({\tilde{x}_{v}^{0}}_{v \in \mathcal{V}}, W, K)$ return $x_{1}^{K}, \dots, x_{n}^{K}$

Algorithm Private gossip-based decentralized SGD [Cyffers et al., 2022]

Initialize $\theta_1^{(0)}, \dots, \theta_n^{(0)} \in \mathbb{R}^p$ for t = 0 to T - 1 do for all nodes v in parallel do $\hat{\theta}_v^t \leftarrow \theta_v^t - \gamma \nabla_{\theta} \ell(\theta_v^t; x_v^t, y_v^t)$ where $(x_v^t, y_v^t) \sim \mathcal{D}_v$ $\theta_v^{t+1} \leftarrow \mathsf{PRIVATE_GOSSIP_AVERAGING}(\{\hat{\theta}_v^t\}_{v \in \mathcal{V}}, W, K, \gamma^2 \sigma^2 \Delta^2)$ return $\theta_1^T, \dots, \theta_n^T$

Theorem ([Cyffers et al., 2022])

After K iterations, Private Gossip Averaging is (α , f)-PNDP with

$$f(u, v) = \frac{\alpha \Delta^2}{2\sigma^2} \sum_{k=0}^{K-1} \sum_{w: \{v, w\} \in \mathcal{E}} \frac{(W^k)_{u, w}^2}{\|(W^k)_{w, :}\|^2} \\ \leq \frac{\alpha \Delta^2 n}{2\sigma^2} \max_{\{v, w\} \in \mathcal{E}} W_{v, w}^{-2} \sum_{k=1}^K \mathbb{P}(X^k = v | X^0 = u)^2,$$

where $(X^k)_k$ is the random walk on graph G, with transitions W.

• As desired, this exhibits the fact that, for two nodes *u* and *v*, privacy guarantees improve with their "distance" in the graph

PRIVACY-UTILITY TRADE-OFF OF PRIVATE GOSSIP AVERAGING

- Recall central DP achieves $O(\frac{\alpha p \Delta^2}{n^2 \epsilon})$ and local DP achieves $O(\frac{\alpha p \Delta^2}{n \epsilon})$
- Setting the mean privacy loss $\overline{\varepsilon}_v = \frac{1}{n} \sum_{u \in \mathcal{V} \setminus \{v\}} f(u, v)$ to satisfy $\overline{\varepsilon} = \max_{v \in \mathcal{V}} \overline{\varepsilon}_v \leq \epsilon$, for private gossip averaging we get (ignoring log terms):

Graph	Arbitrary	Complete	Ring	Expander
Utility (MSE)	$\frac{\alpha p \Delta^2 d}{n^2 \epsilon \sqrt{\lambda_W}}$	$\frac{\alpha p \Delta^2}{n\epsilon}$	$rac{\alpha p \Delta^2}{n\epsilon}$	$\frac{\alpha p \Delta^2}{n^2 \epsilon}$

- We match the utility of central DP up to an additional $d/\sqrt{\lambda_W}$ factor, where d is the max degree and λ_W of the spectral gap of W
- Some graphs (e.g., expanders) make this constant: we get privacy and efficiency!
- Note: we also have extensions to time-varying graphs and randomized gossip

Theorem ([Cyffers et al., 2022])

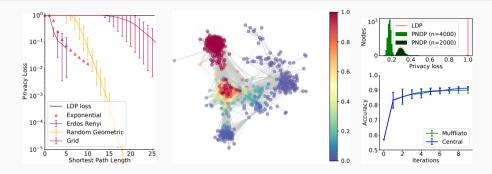
Let F be μ -strongly convex, F_v be L-smooth and $\mathbb{E}[\|\nabla \ell(\theta^*; x_v, y_v) - \nabla F(\theta^*)\|^2] \le \rho_v^2$. Let $\bar{\rho}^2 = \frac{1}{n} \sum_{v \in \mathcal{V}} \rho_v^2$. For any $\epsilon > 0$, and appropriate choices of T and K, there exists f such that the algorithm is (α, f) -PNDP, with:

$$\forall v \in \mathcal{V}, \quad \overline{\varepsilon}_{v} = \frac{1}{n} \sum_{u \in \mathcal{V} \setminus \{v\}} f(u, v) \leq \epsilon \quad and \quad \mathbb{E}[F(\overline{\theta}^{1:T}) - F(\theta^{\star})] \leq \tilde{\mathcal{O}}\left(\frac{\alpha p \Delta^{2} d}{n^{2} \mu \epsilon \sqrt{\lambda_{W}}} + \frac{\overline{\rho}^{2}}{nL}\right),$$

where d_v is the degree of node v and λ_W is the spectral gap associated with W.

- The term $\frac{\bar{\rho}^2}{nl}$ is privacy-independent and dominated by the first term
- The first term has the same form as before, so same conclusions apply!
- In particular, with an expander graph, we match the privacy-utility trade-off of centralized SGD with a trusted curator (up to log terms)

EMPIRICAL ILLUSTRATION



- Users get local DP guarantees w.r.t. their direct neighbors but stronger privacy w.r.t. to other users depending on their distance and the mixing properties of the graph
- This fits the privacy expectations of users in many use-cases (e.g., social networks)
- For learning, we can randomize the graph after each local computation step to make the privacy loss concentrate!

CONCLUSION & PERSPECTIVES

Take-home message

• Decentralized learning can amplify differential privacy guarantees, providing a new incentive for using such approaches beyond the usual motivation of scalability

Perspectives

- Privacy and utility guarantees for random walk-based decentralized SGD on arbitrary graphs [Johansson et al., 2009], possibly with multiple parallel walks [Hendrikx, 2022]
- Capturing the redundancy in gossip-based communication (i.e., correlated noise) to further improve privacy guarantees (recall that even constants matter in DP!)

THANK YOU FOR YOUR ATTENTION! QUESTIONS?

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